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# Threat Model for Environmental Sensing and Terrain Reasoning

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# Threat Model for Environmental Sensing and Terrain Reasoning

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# Agenda

- **Background.**
- **Combat M&S Issues & Needs.**
- **Threat Model Overview.**
- **Related Work.**
  - US Army's COMBAT XXI.
  - ONR's BASE-IT prototype.
- **COMBAT XXI & BASE-IT Comparison.**
- **Summary.**

# Background

- Current operations require that military forces be able to construct **and protect a 300-person combat outpost or patrol base** with integrated sensing and defense capabilities.
- The Deployable Force Protection (DFP) Technology Focus Team (TFT) identifies **technology enabled-capabilities to meet force protection needs** for forces operating remotely in small bases.
  - Integrated, lightweight protection technologies.
  - Line-of-sight and non-line-of-sight detection.
  - Organic active and passive defense.
  - Robust and resilient systems.
- The TRADOC Analysis Center (TRAC) in partnership with NPS and the MOVES Institute support to DFP TFT:
  - **Gap analysis** to assess and prioritize gaps in current force protection capabilities.
  - **M&S** to determine the operational impact of force protection capabilities.

# Combat M&S Issues & Needs

- **Representation of cognition in most combat M&S has lagged behind current technology and acquisition trends.**
  - Current combat models and simulations have **limited ability to model entity interactions with the battle space environment.**
- **Current demands on combat M&S and the need to represent DFP capabilities require intelligent behaviors for:**
  - Environmental sensing.
  - Terrain reasoning.
  - Intelligent target search.
  - Knowledge management.
  - Other decision-making behaviors.
- **There is a stated need and interest from the M&S community for a threat model capability.**

# Threat Model Overview

- Leverages several detailed models of individual combatant behaviors developed by TRAC and MOVES.
- A prototype model that **augments the simulation of interactions** of entities with the battle space.
- Creates **environmental sensing knowledge sets** to support terrain reasoning to include dynamic situations.
  - Target search, route selection, emplacement of tactical positions.
  - Locating nearby cover, planning concealed paths, moving in formation, selection of movement technique, assessment of enemy positions.
- **Components:**
  - Terrain analysis program.
  - Model of invisible threats.
  - Search and movement model.

***Goal is to represent individuals and units that realistically search for threats, keep an updated model of likely threat positions, and dynamically replan their movements.***

# Threat Model Overview

## Terrain Analysis Program

- An **offline program** for entities in the simulation to take into account terrain in their planning, decisions, and actions.
  - Terrain representation.
  - Functions to construct, query, and manipulate the terrain representation.
- **Leverage line of sight and computer vision-like techniques to characterize the terrain.**
  - **Intervisibility** between points.
  - **Detection** probability and time.
  - **Cover** affordance (including cover from particular threat directions).
  - **Suitability** of positions for distinct actions (sniping, ambush, etc.)
- **Utilize hierarchical navigational graphs to feed ACQUIRE-like target acquisition models in a scalable manner.**
  - Pre-computed visible surface area and contrast to background information.

# Threat Model Overview

## Model of Invisible Threats

- A **dynamic model of the distribution of perceived threat** to improve behaviors for target search, planning, and maneuver.
- Threat probability model incorporating **Bayesian statistical model**.
  - Accounts for the **prior distribution of threat** in the environment and the **unit's observations of the environment**.
- Depends on pre-computed acquisition parameters from the terrain analysis module.
- Subjective to the entities in the simulation.
  - Individual or group of combatants.
- It accounts for the fact that threats can move.



# Threat Model Overview

## Search and Movement Model

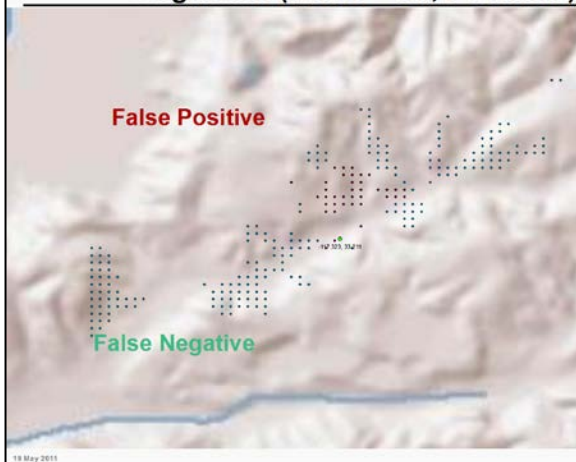
- An **integrated model search and movement** behavior system for improved search, movement planning, and finding paths taking tactical information into account.
- Takes into account **factors and doctrinal aspects of unit movement** such as:
  - Dynamic movement control (speed, direction, orientation).
  - Maintenance of proper dispersion.
  - Exploitation of cover and micro-terrain.
- Relies on pre-computed intervisibility & acquisition parameters from the terrain analysis model and the model of unseen threats.

# Related Work: COMBAT XXI

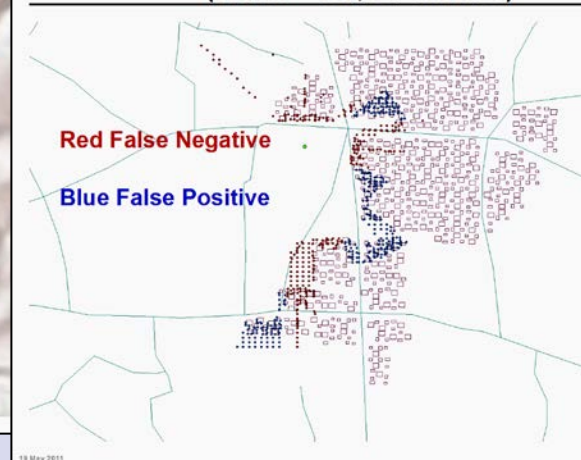
## Pre-computed line of sight (LOS) methods:

- **Point based.**
  - Coarse grid of nodes to approx. true LOS.
- **Sector based.**
  - Nodes are grouped by sector, for each node, defined by bearing and range bands.
  - If the node has LOS to any node in a sector, then it is assumed to have LOS to the sector.

Version 2 Sector Based False Positives and Negatives. (cutoff = 0.5, 8 Sectors)

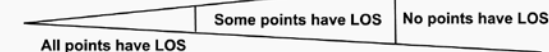


False Positive/Negative Flat terrain (cutoff = 0.3, 16 sectors)



## Version 2 Sector Based Pre-calculated LOS

- Based on "Killzone's AI: Dynamic Procedural Combat Tactics"
- For each node, the following data are calculated for each sector.
  - A range that the node has LOS to all nodes.
  - A range beyond which the node has no LOS.
  - The proportion of the nodes in the middle that have LOS.
- At model runtime
  - The estimated LOS is true if the range to the node of interest is less than the "all LOS range".
  - False if the range is greater than the "no LOS range".
  - If the range is in the middle region
    - If "use actual in middle" is true, then the actual LOS is returned.
    - Otherwise, true is returned if the proportion of nodes with LOS is above a user specified value.
    - Based on limited (2 scenarios) testing the most accurate cutoff is approximately 0.3.



## Pre-computed LOS Performance Comparison

- Camp Pendleton: 16.4 km<sup>2</sup>, 50m node spacing, 3% covered with buildings. 7340 / 7994 nodes. (8 Sectors)

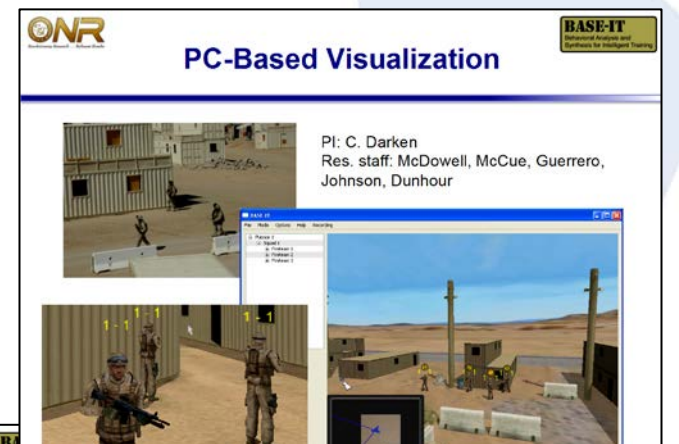
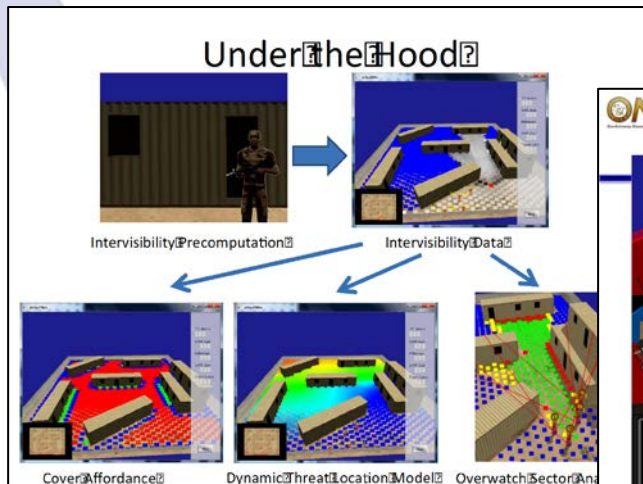
	Point Based	Sector Based 2 (0.3 cutoff)	Sector Based 2 (actual in middle)
False Positive	0.1%	3.9%	0.02%
False Negative	5.0%	6.0%	1.0%
Speed (over actual LOS)	35% faster	63% faster	51% faster
LOS file size	126M	4.5M	4.5M

- Fictitious Flat Terrain: 1.7 km<sup>2</sup>, 20m node spacing, 40% covered with buildings. 7491 / 7999 nodes. (8 Sectors)

	Point Based	Sector Based 2 (0.3 cutoff)	Sector Based 2 (actual in middle)
False Positive	1.0%	2.7%	0.1%
False Negative	2.0%	5.3%	0.4%
Speed (over actual LOS)	25 times faster	24.5 times faster	3.5 times faster
LOS file size	141M	4.4M	4.4M

## Related Work: BASE-IT (1 of 2)

- **BASE-IT is a standalone US Marine Corps training application.**
  - Prototype tool with novel algorithms to simulate fireteam movement and visual scanning appropriate to urban environments.
- **Contributions:**
  - Coordinated movement.
  - Realistic visual search & target detection.
- **Enabler: Threat Probability Model.**

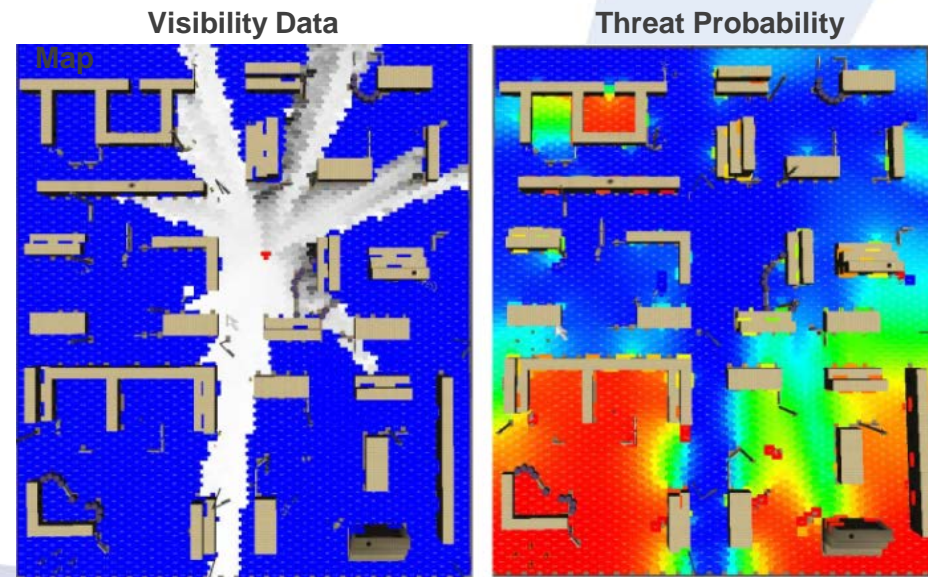
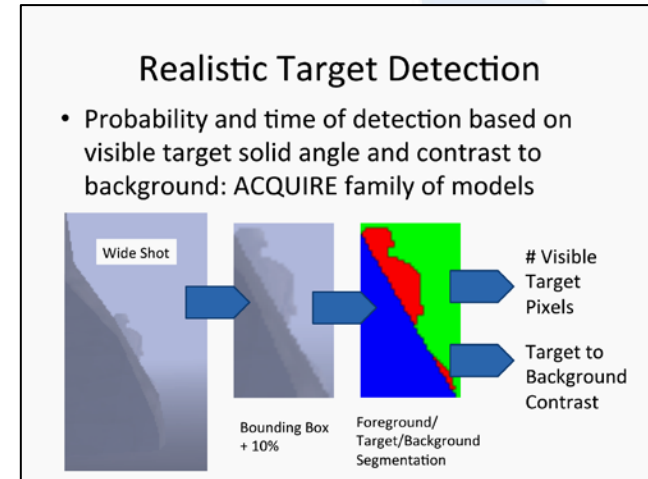




# Related Work: BASE-IT (2 of 2)

## Threat Probability Model

- **Threat map: probability distribution providing a subjective estimate of the threat's location.**
- **Variant of ACQUIRE detection model based on pre-computed target size and contrast values.**
- **Dynamic hierarchical representation with fine detail near the observer, coarser far from observer.**
- **Improved visual search behavior prioritizing locations that are most likely to contain a threat.**



*Pre-computed contrast values from a single red point (whiter is better).*

*Threat probability map of a fireteam that has explored most of the upper right region (hot colors represent high perceived threat values).*

# COMBAT XXI & BASE-IT Comparison

- **Model Infrastructure.**
- **Terrain representation.**
- **Sensing.**
- **Detection.**
- **Visual Search.**
- **Movement.**

# Summary

- **Summary.**
  - There is a need to represent more realistic intelligent behaviors in combat M&S with enough detail to estimate the operational effectiveness of DFP capabilities.
  - A threat model capability that takes the battle space and threat into account to improve the representation of behaviors for target search, planning, and maneuver would increase realism in combat M&S.
- **Way Ahead.**
  - Exploit the specific advantages of the techniques and algorithms developed for COMBAT XXI & BASE-IT to improving the overall representation of cognition.
  - Continue assessment of requirements, development, and implementation of the threat model prototype capability.

# Questions?

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